

Feature Recognition for Photogrammetry Calibration of the Super-Kamiokande Detector

Weekly update
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Outline

Introduction

Problem Statement

Methods

Result

Future Work

Introduction

Neutrino

- Subatomic particle that is very similar to an electron but has no electrical charge.
- One of the most abundant particles in the universe.
- Incredibly difficult to detect.

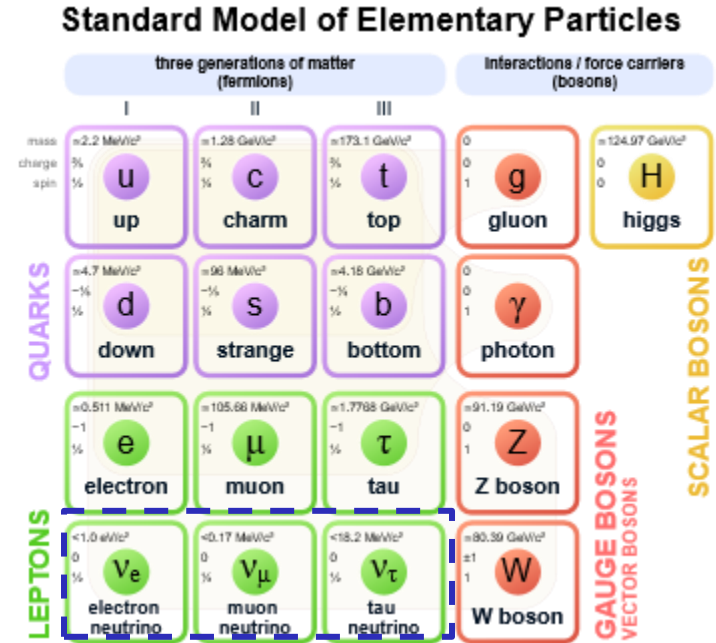


Fig: standard model[1]

How is neutrino detected?

Super Kamiokande (Super-K)

1



Fig: Model of Super-Kamiokande detector[2]

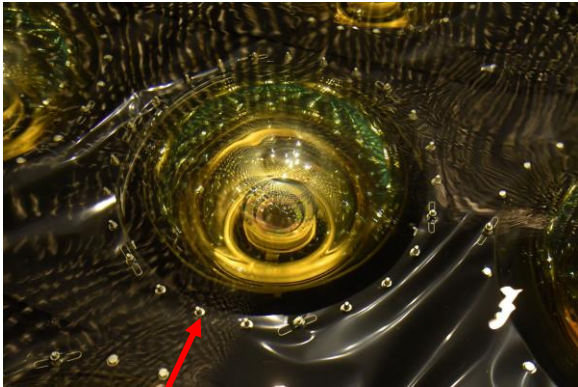
~11,000 PMTS

2



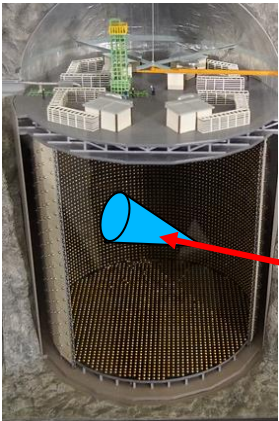
PMT[3]

3



Bolts for mounting PMT to wall.

4



Cherenkov radiation

- Produced when charged particles move faster than speed of light in a medium(water).[2]

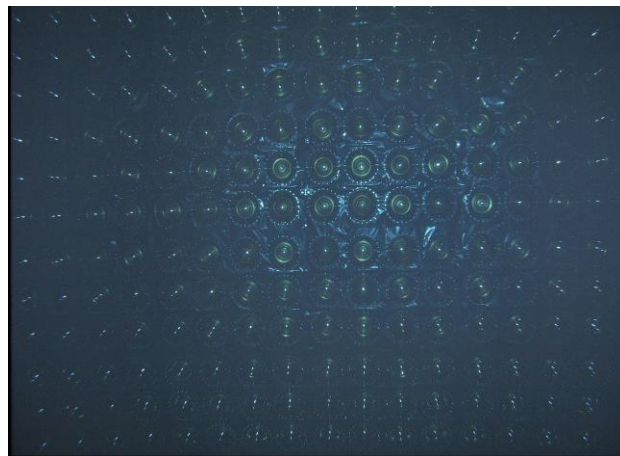
Photographing detector wall with Underwater drone

1



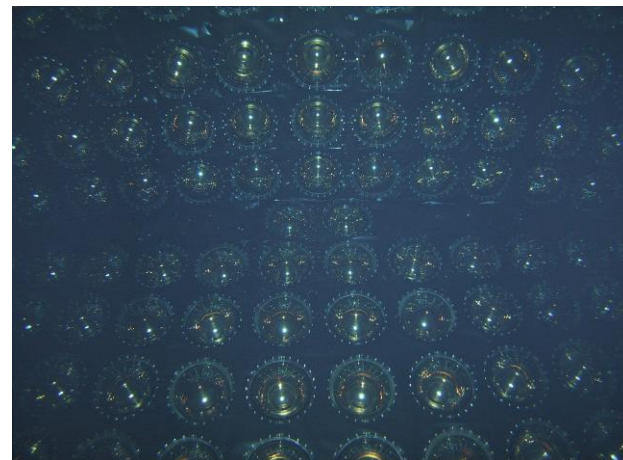
>15000 img

2



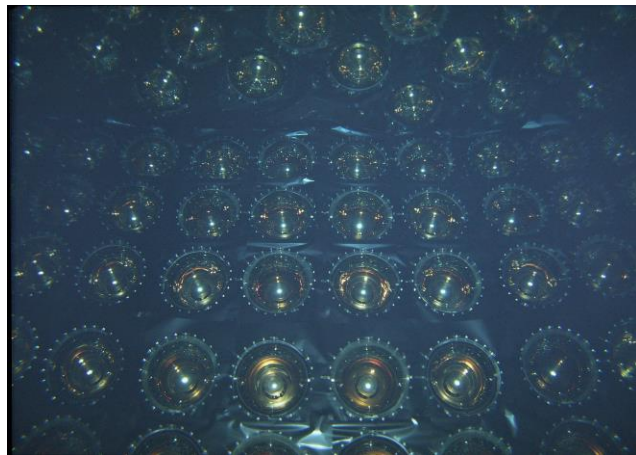
239.jpg

3



379.jpg

4



Need for automation?

Problem Statement

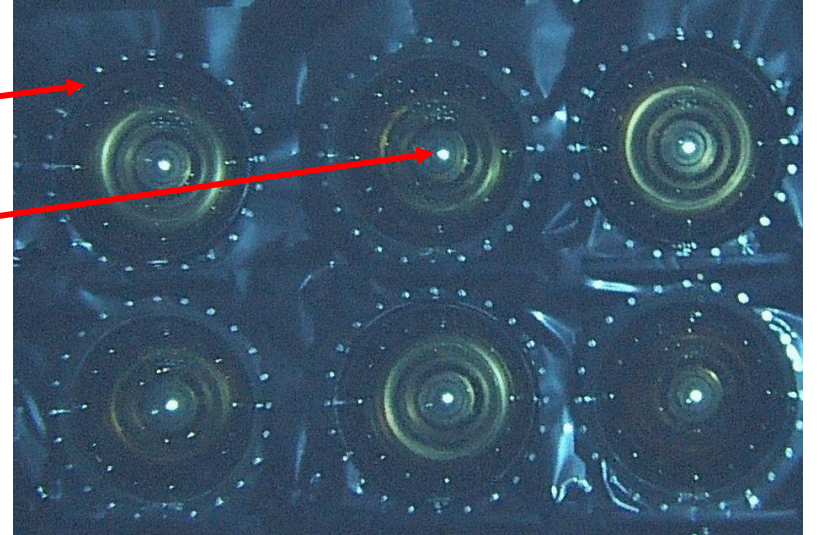
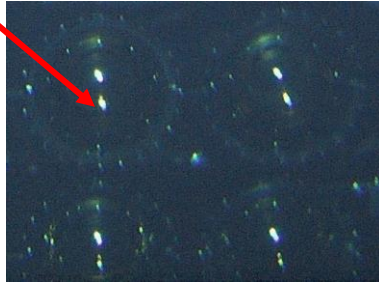
- Find Location of PMTs in detector wall using photographs taken.

Noticeable features

1) Bolts

2) Dynode centre

-Sometimes they are not the centre of PMT. Instead the reflection from dome.



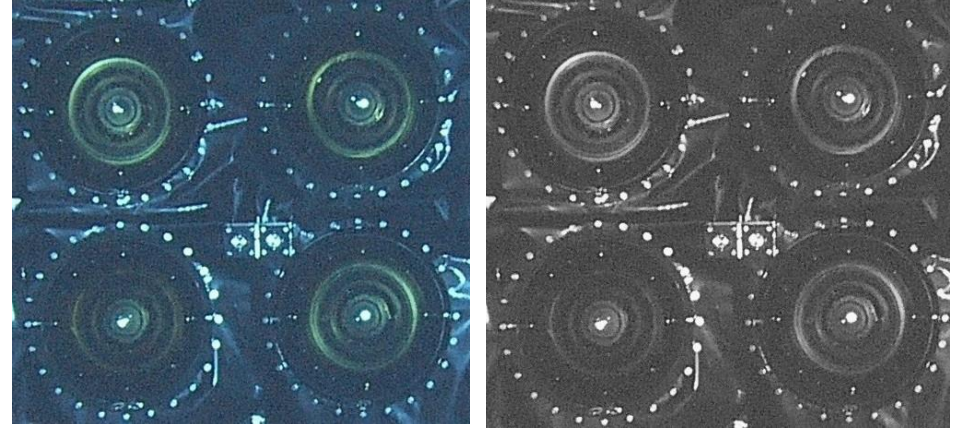
Noticeable Properties

- 1) Bolts are evenly spread in circumference.
- 2) PMTs do not overlap with each other.

Method

1. Bilateral Filtering

Removes noise in images while preserving sharp edges.



Example of Filtering
($d=5$, $\text{sigColor}=2$, $\text{sigSpace}=50$)

2. Blob detection

Blob: *In computer vision, blob detection methods are aimed at detecting regions in a digital image that differ in properties, such as brightness or color, compared to surrounding regions.*

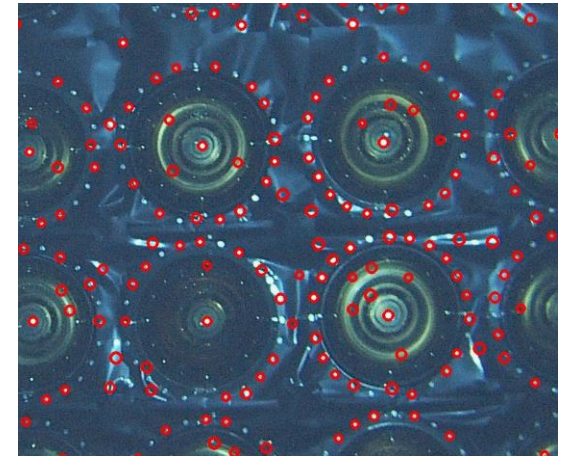
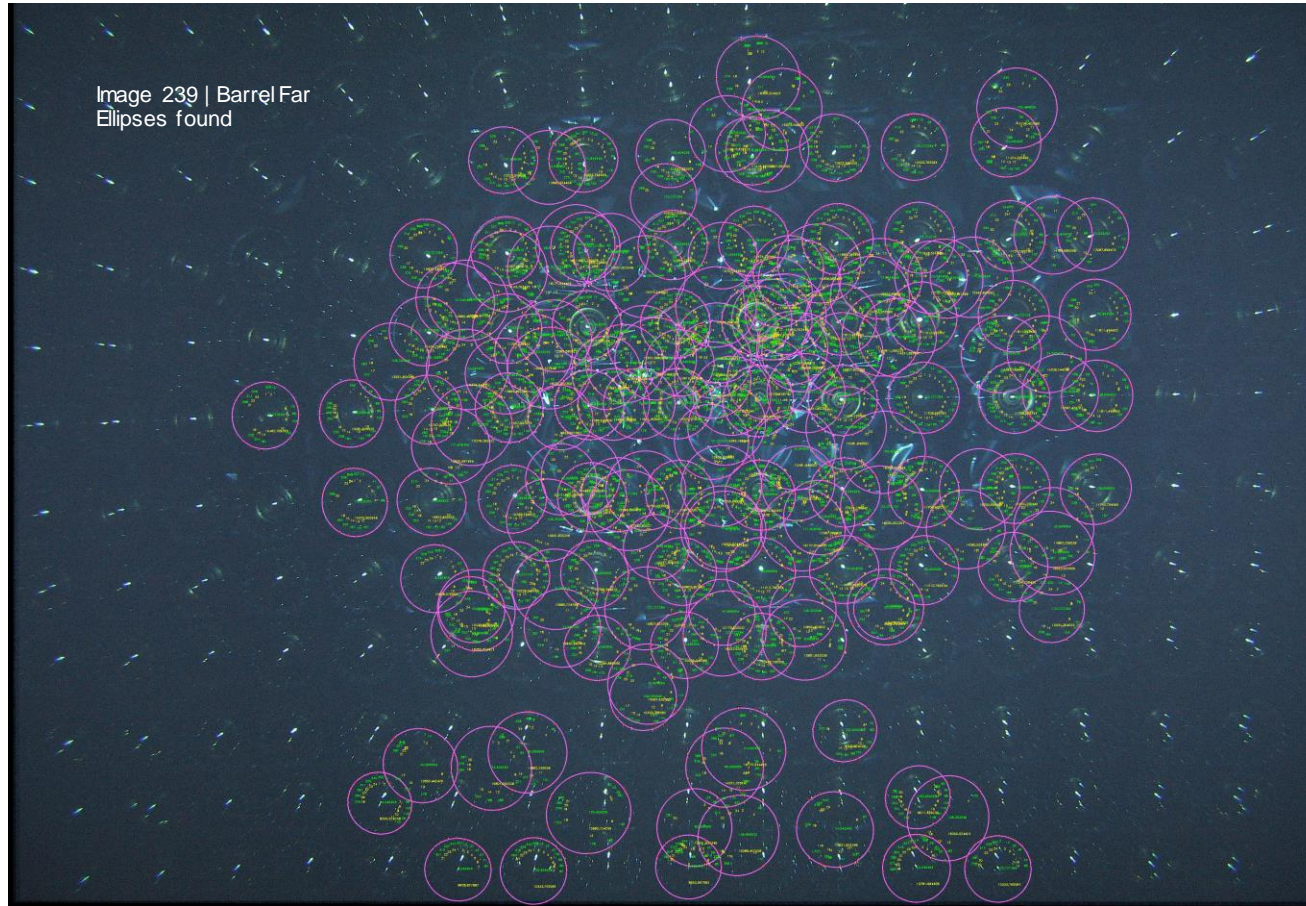


Fig: *Image of detector wall.
Red circle represents candidate bolt.*

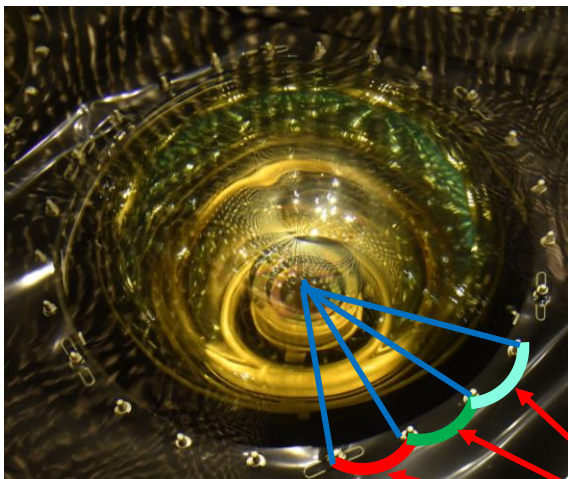
3.Hough-Ellipse Transform



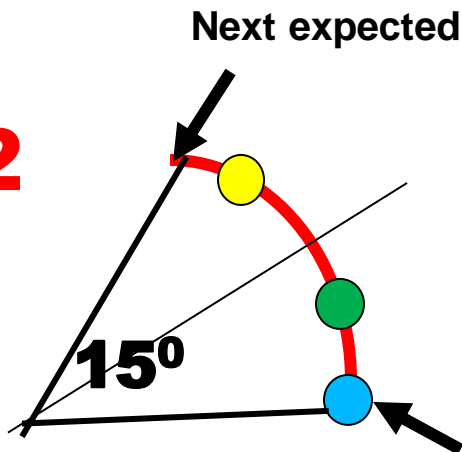
- Finds many overlapping ellipses
- Need to remove overlapping ellipses and keep ones that are PMTs

4. Bolt angle cut

1



2



3



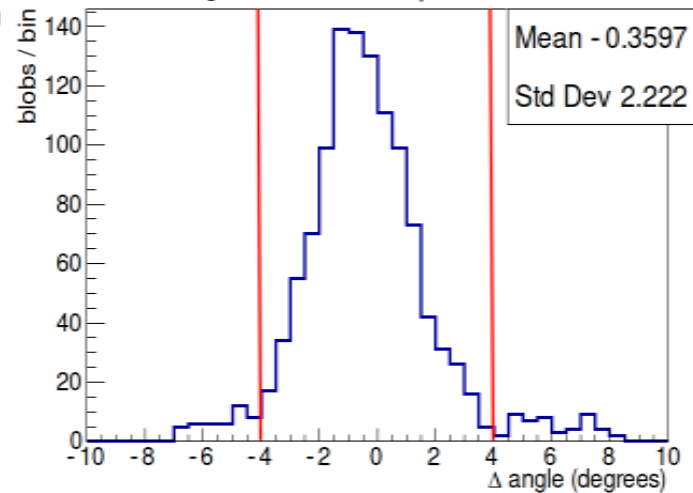
Remove these

15°

- Cut bolts that are more than $\pm 4^\circ$ from expectation.
- If angle between two blobs is less than $7.5 = 15/2$ remove the one with more deviation.

4

Angle of bolt from expected



Shown for BarrelSurveyFar Image 239, for all ellipses found

5. Ellipse Overlap cut

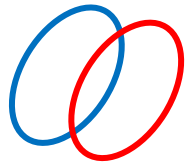
PMTs shouldn't overlap.

If two ellipses intersect:

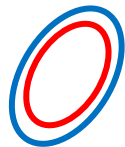
- Correct ellipse is one with more of bolts.

If ellipse is contained:

- False if contained with less bolts.

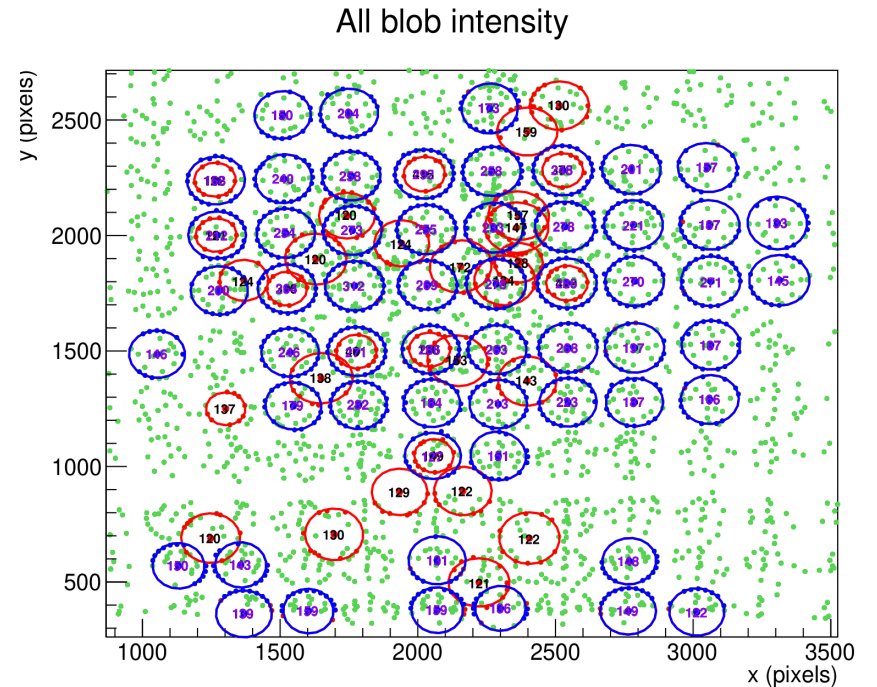


overlap



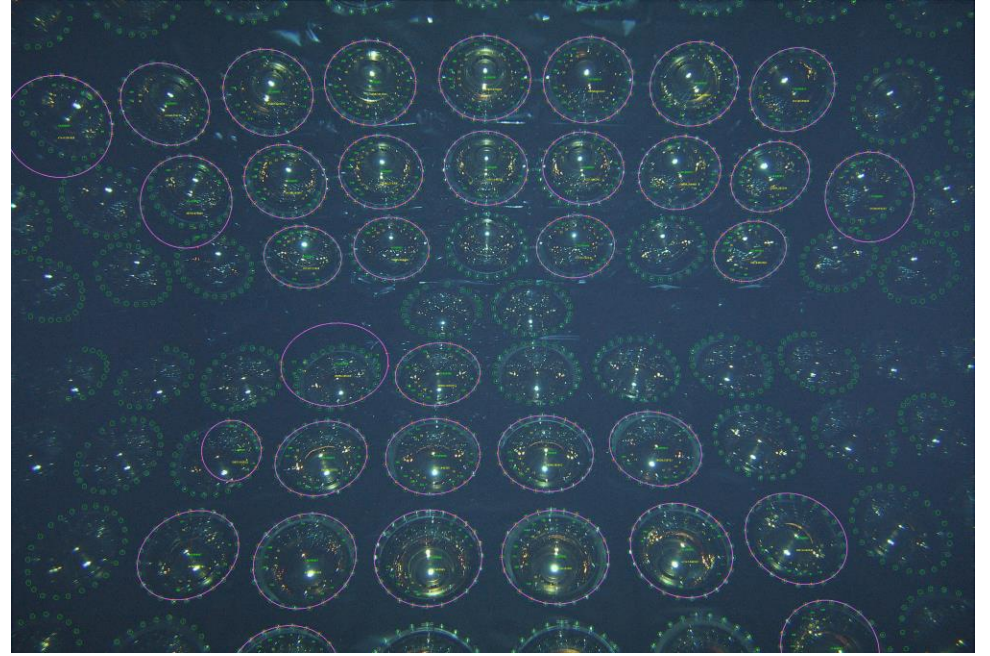
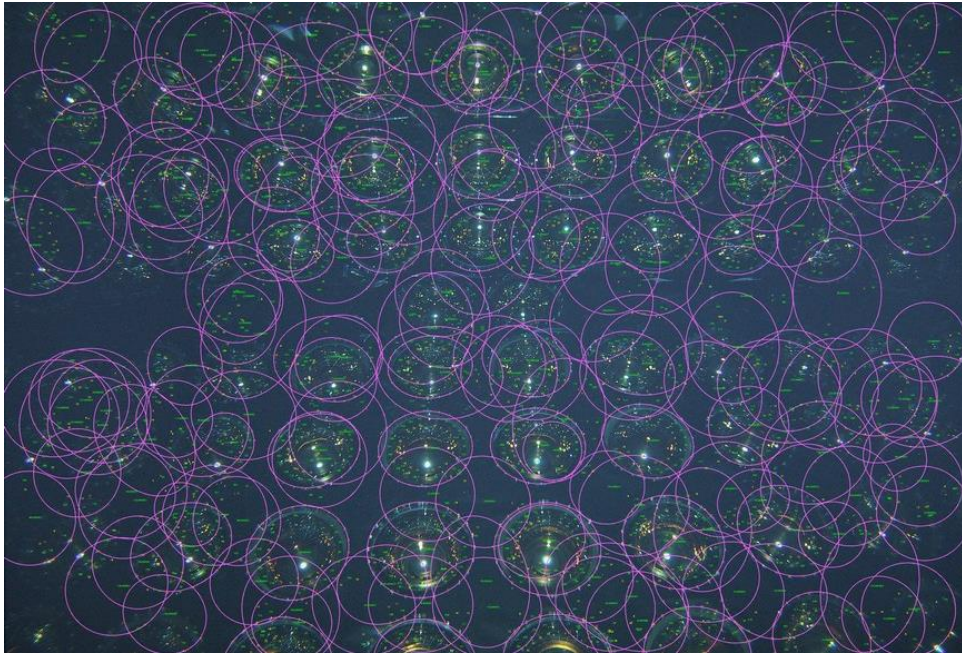
contained

- Two ellipses overlap.
- One ellipse Contain another.
- Sent corrections to algorithm that we followed – (non-peer reviewed) publication updated.



Final Image
(Barrel Far 239)

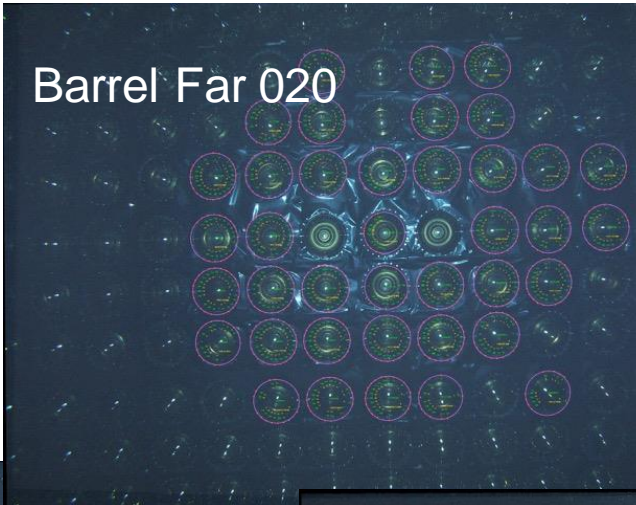




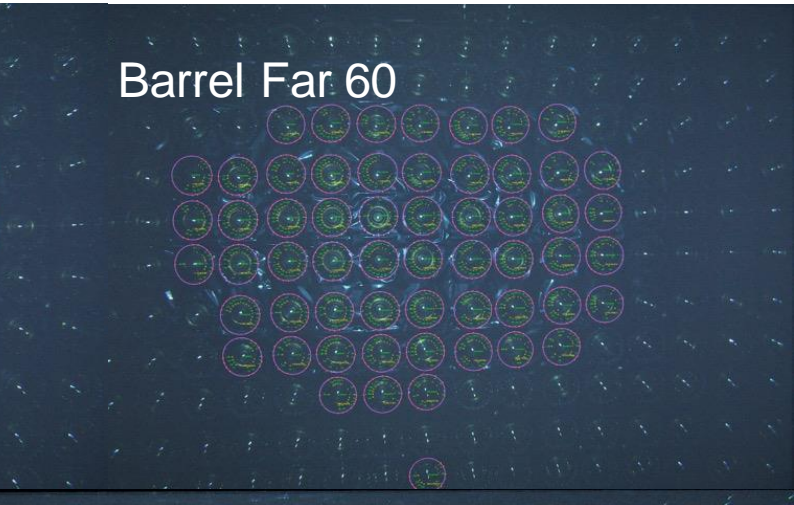
- **Fig:** Image 379 | BottomCornerSurvey
- Also works when PMTs are elliptical.

Gallery of Success

Barrel Far 020



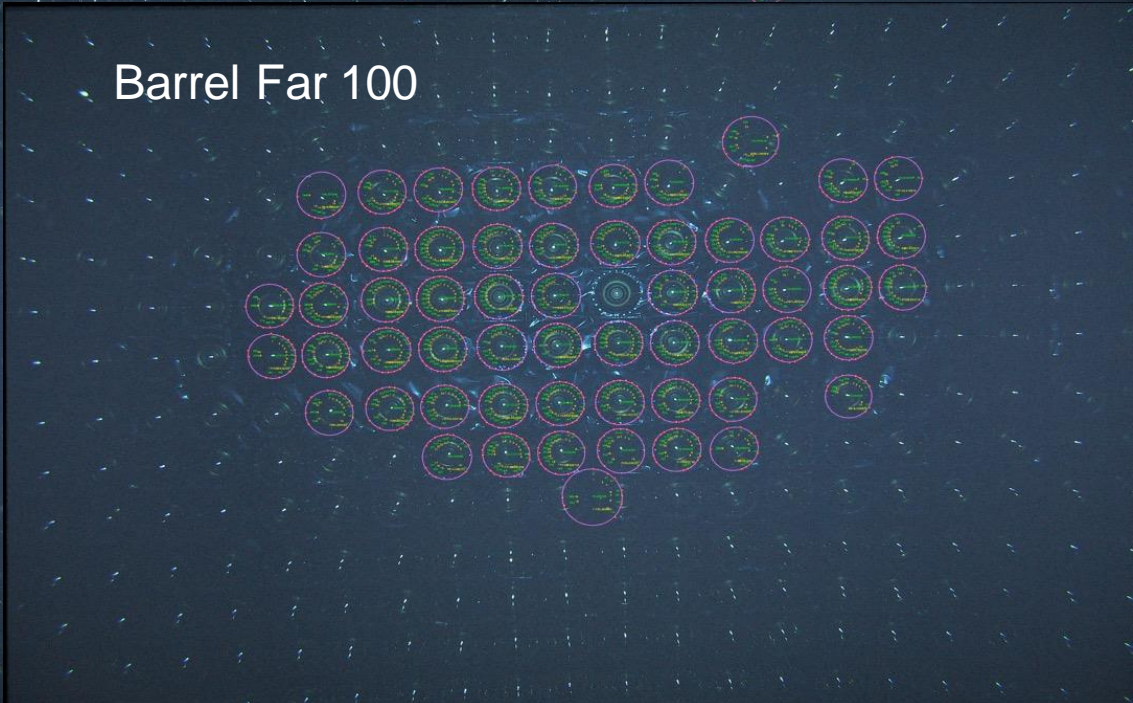
Barrel Far 60



Barrel Far 010

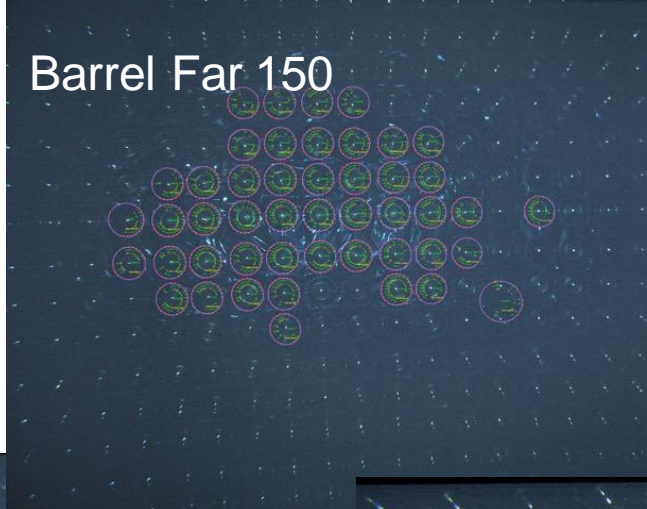


Barrel Far 100

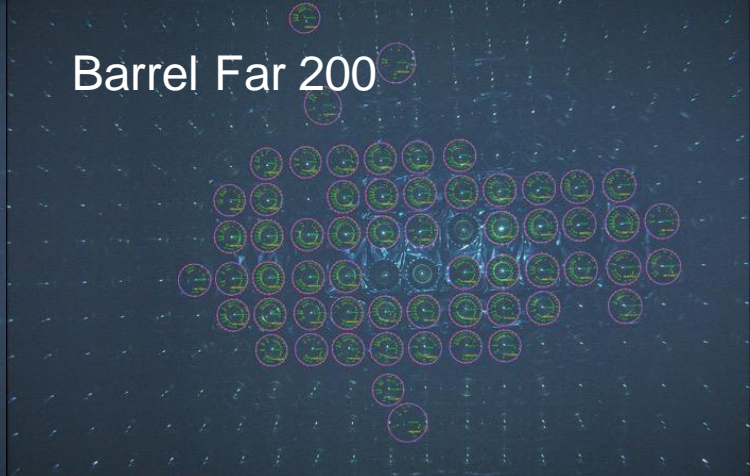


Gallery of Success

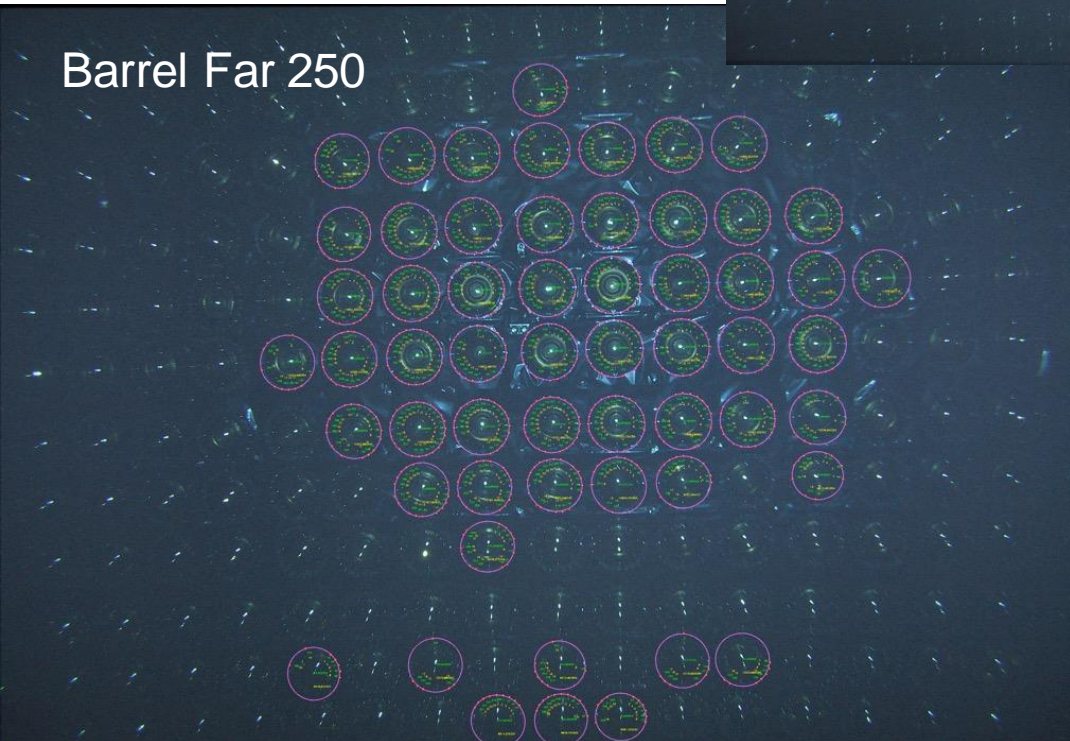
Barrel Far 150



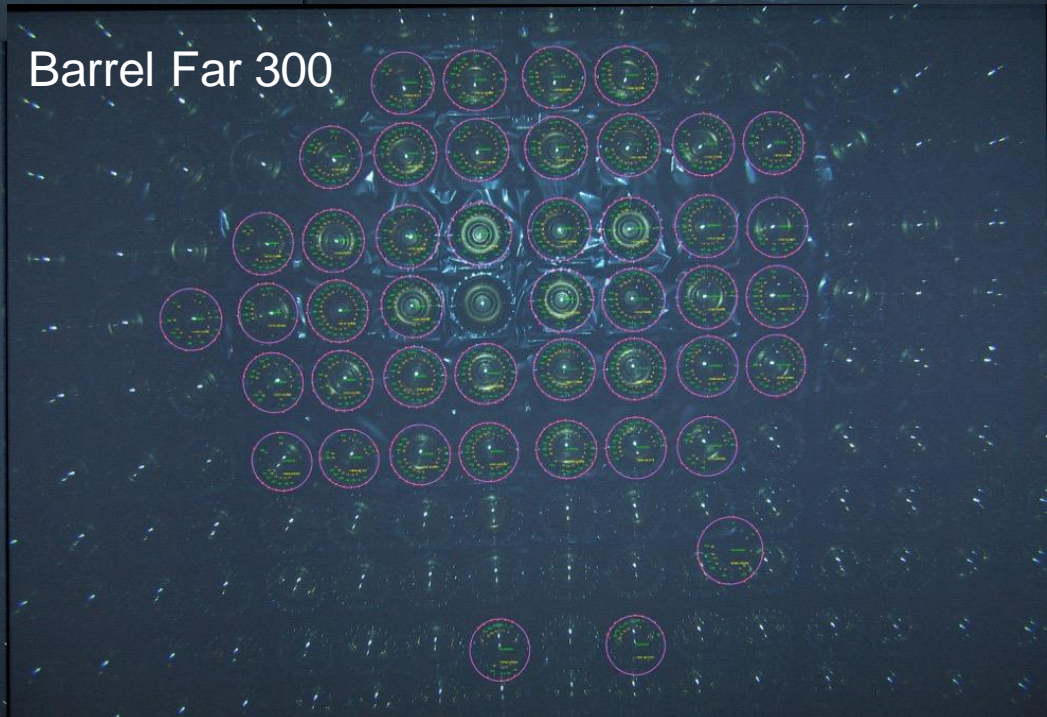
Barrel Far 200



Barrel Far 250



Barrel Far 300



Future Work

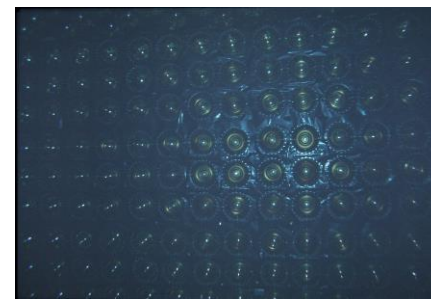
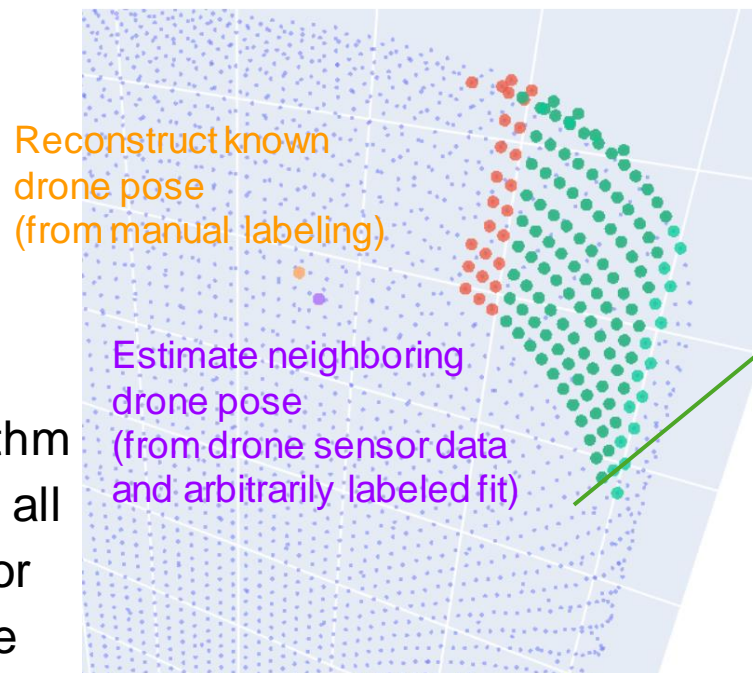
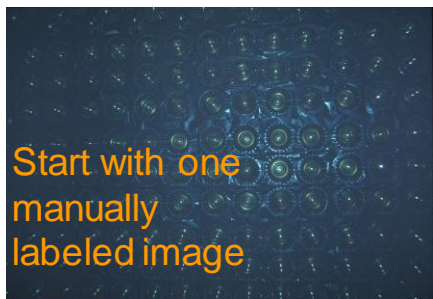
- Process all images and reconstruct the geometry of whole Super-K detector.

References

- [1] "Standard model of elementary particles" by chriswalf, is licenced under CC-BY-SA-3.0
- [2] "スーパーカミオカンデタンク内公開 Super-Kamiokande insidetank" by nvslive is licensed under CC BY-NC 2.0
- [3] "Photomultiplier Tube (PMT) at Kamioka SkyDome" by kwanet is licensed under CC BY 2.0

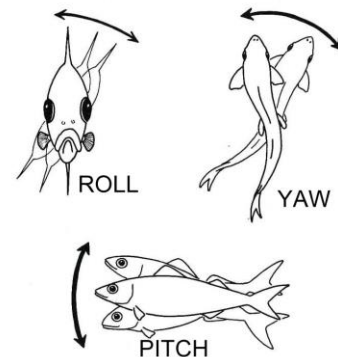
Appendix

PMT Labeling



Project PMT labels onto neighboring photo

- Developing an algorithm to automatically label all the PMTs and bolts (or super-modules) in the whole photo set.

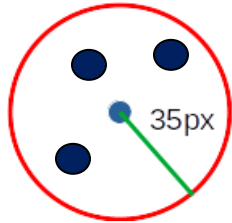


Drone sensor gives drone pose (yaw, pitch, roll angle heading and depth).

3.Blob density cut

Problem:

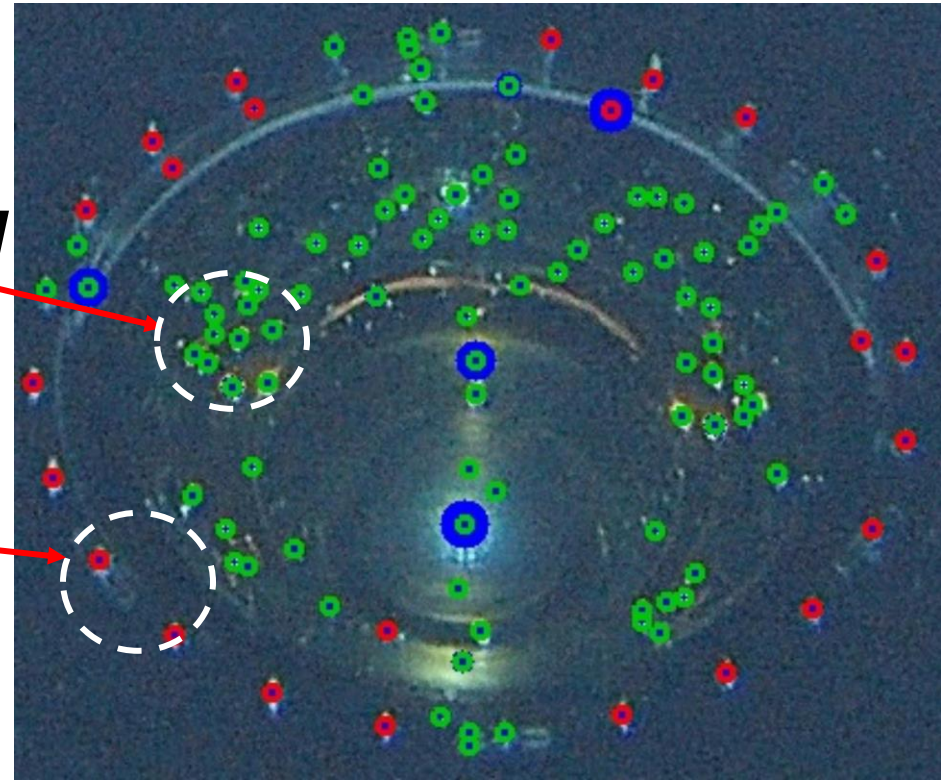
- More unwanted features.
- Images from corner of tank.
- *Unwanted features are clustered.*



Count no. inside circle.

Unwanted

want



Blue = all blobs
Red = kept blobs
Green = rejected blobs